**CS 33** 

**Storage Allocation** 

### Finding the Right Free Block

Free (28 bytes) **Allocated** Free (40 bytes) **Allocated** Free (32 bytes) **Allocated** 

malloc(24)

- Search strategies
  - first fit
  - best fit

#### **A Problem**

- A malloc request is for a block of 32 bytes
- The block found on the free list is 1024 bytes long
- Should malloc return a pointer to the entire 1024-byte block?

### **Splitting**

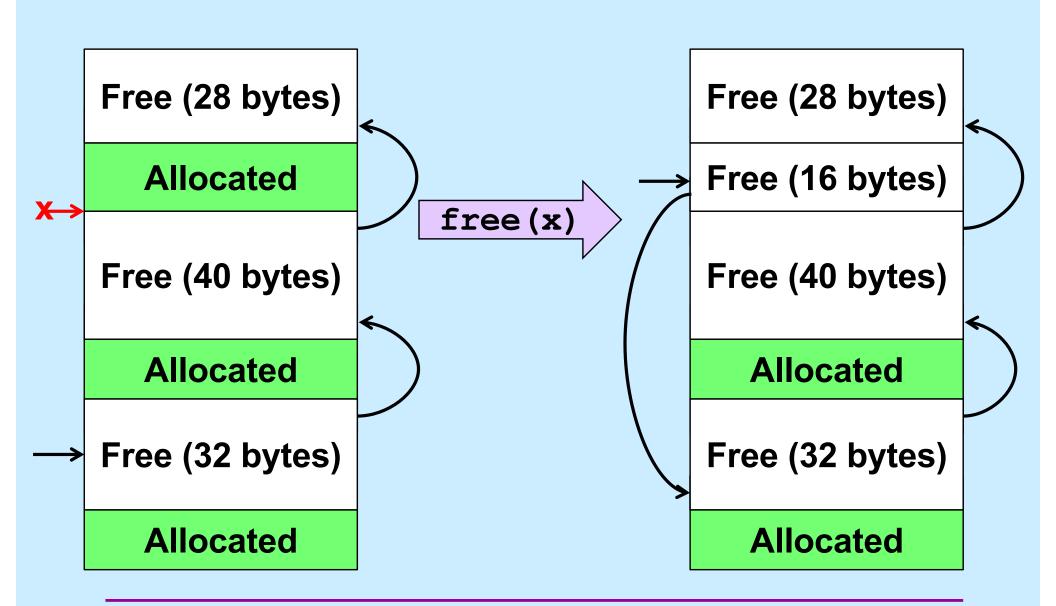
Free (1024 bytes)



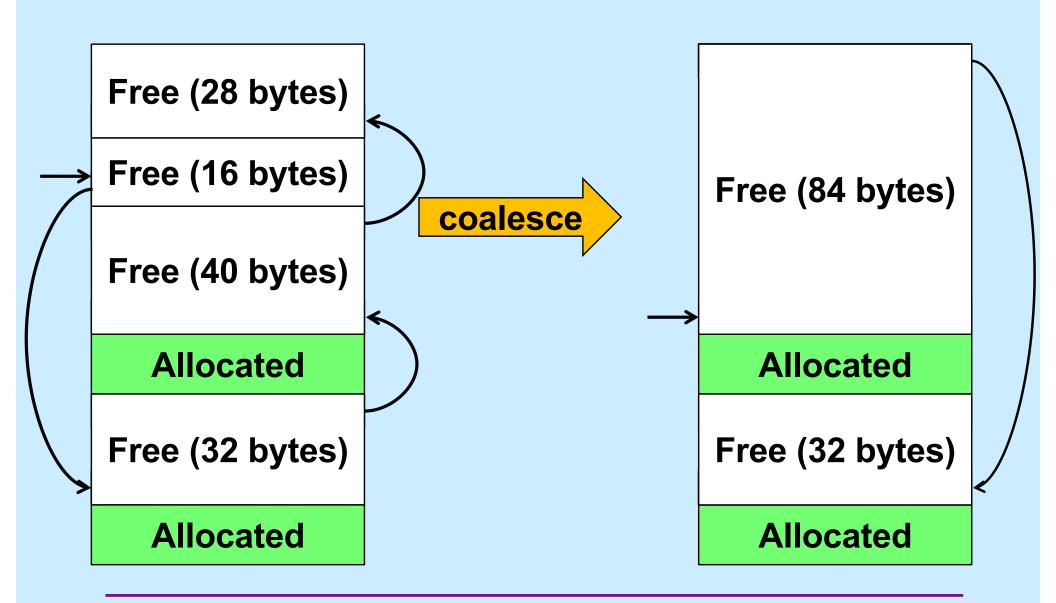
Free (992 bytes)

**Allocated** 

#### **Another Problem**



### Coalescing



#### Quiz 1



We have two free blocks of memory, of sizes 1300 and 1200 (appearing in that order). There are three successive requests to *malloc* for allocations of 1000, 1100, and 250 bytes. Which approach does best? (Hint: one of the two fails the last request.)

- a) first fit
- b) best fit

#### **Allocation**



#### **Some Observations**

#### Best fit

- perhaps leaves behind chunks that are too small to be of use
- requires linear time (in size of free list) for malloc

#### First fit

- small chunks congregate at beginning of free list
- upper bound of linear time for malloc, but often much less

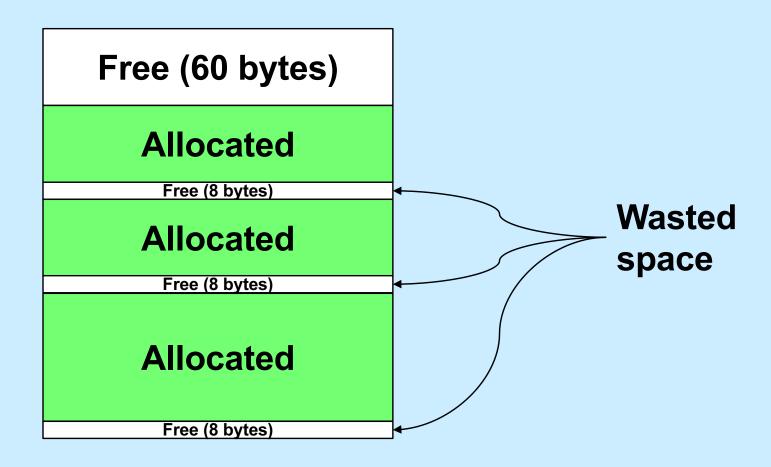
### **Fragmentation**

- Fragmentation refers to the wastage of memory due to our allocation policy
- Two sorts
  - external fragmentation
  - internal fragmentation

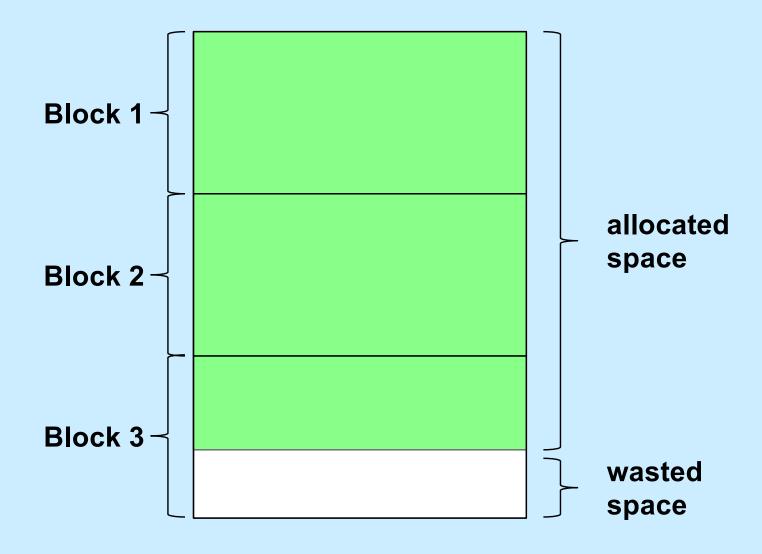
### **Fragmentation**

- Fragmentation refers to the wastage of memory due to our allocation policy
- Two sorts
  - external fragmentation
  - internal fragmentation

### **External Fragmentation**



# **Internal Fragmentation**



#### **Variations**

- Next fit
  - like first fit, but the next search starts where the previous ended
- Worst fit
  - always allocate from largest free block
    - » perhaps reduces the number of "too small" blocks
- Free-list insertion
  - LIFO
    - » easy to do
    - » O(1)
  - ordered insertion
    - » O(n)

#### Quiz 2

Assume that best-fit results in less external fragmentation than first-fit.

We are running an application with modest memory demands. Which allocation strategy is likely to result in better performance (in terms of time) for the application?

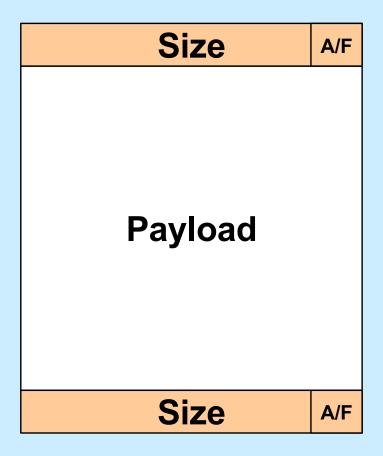
- a) first-fit with LIFO insertion
- b) first-fit with ordered insertion
- c) best-fit

### **Data Structure Requirements**

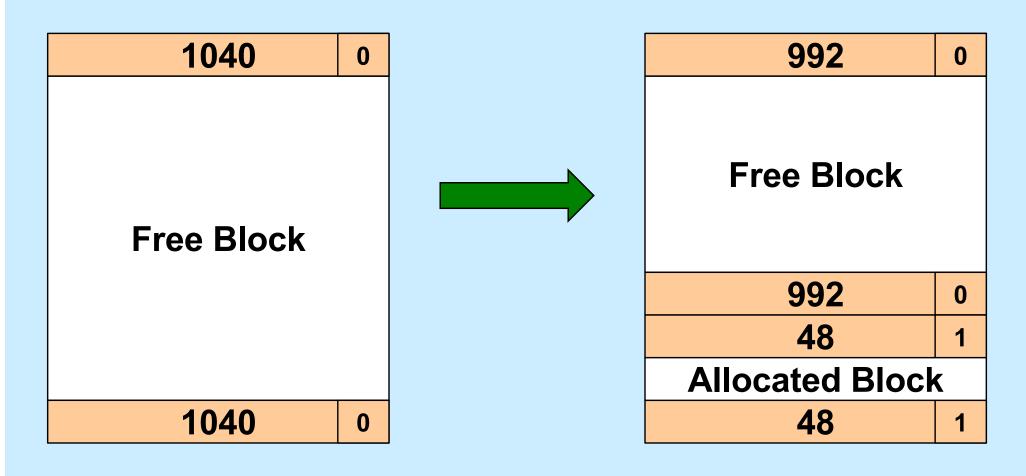
#### All blocks

- we need to know how big they are
  - » when free is called, it must be known how much to free
  - » when looking at a free block in malloc, we need to know its size
- we need to know which they are: free or allocated
  - » needed for coalescing
- Free blocks
  - they need to be linked into the free list

### **Solution: Boundary Tags**



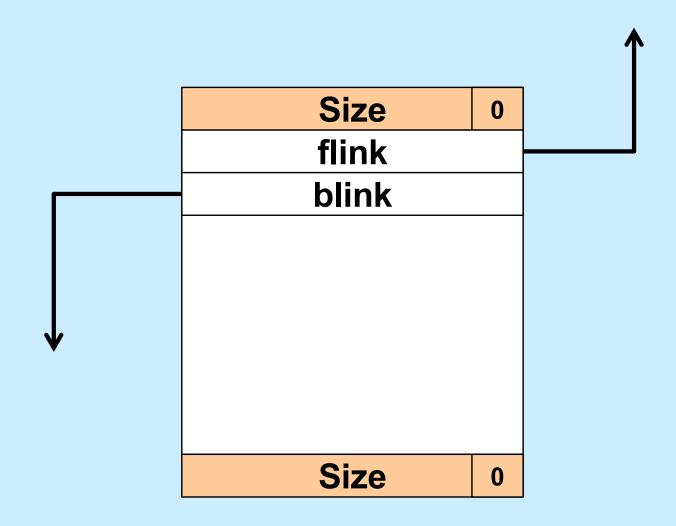
# Splitting a Block

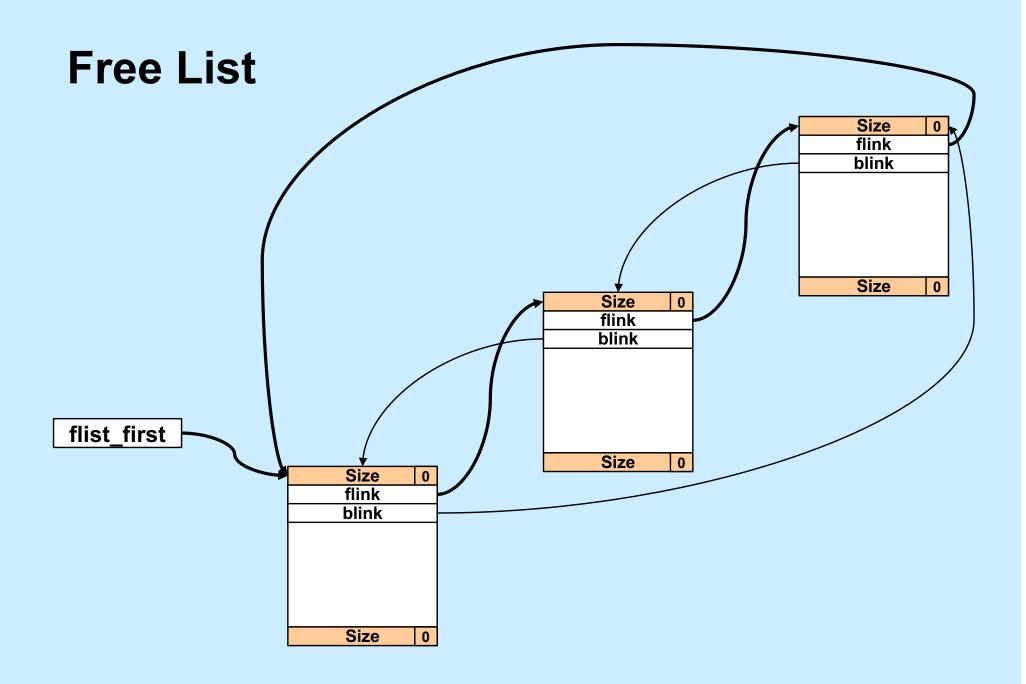


### Representing the Free List

- We need a pointer to the first element
  - flist\_first
- We need to traverse the list from beginning to end
  - required by malloc
- We need to merge adjacent blocks
  - this may require removing a block from the free list, then reinserting it (as part of a coalesced block)
- Links may be put in the free block's payload area
  - not needed for allocated blocks!

# Free Block Representation





#### Quiz 3

#### Why is the free list doubly linked?

- a) we don't really need it to be doubly linked for malloc and free, but it may be necessary for some future operations
- b) to facilitate sorting the free list
- c) so we can traverse it in both directions
- d) so that, given a pointer to an arbitrary free block, we can easily remove the block from the list

#### Quiz 4

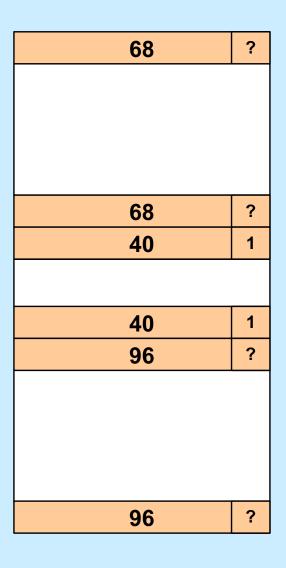
#### Why is the free list circular?

- a) to facilitate implementing the next-fit search strategy
- b) so that we don't have to special-case the the handling of the first and last list elements
- c) both of the above
- d) none of the above

### Heap ≠ Free List

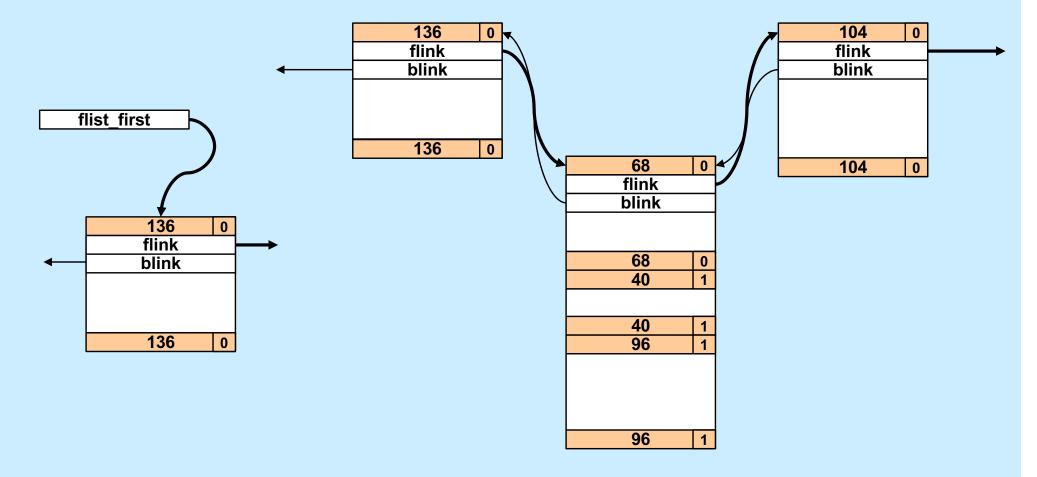
- Heap
  - collection of all memory usable as dynamic storage: the dynamic portion of the address space
    - » both allocated and free
- Free list
  - those blocks of the heap that are free
    - » linked together (circular, doubly)
- Both important, but different
- Confusion: what does next block mean?
  - next adjacent block (next in heap)
  - next free block (next in free list)

### **Coalescing Revisited**

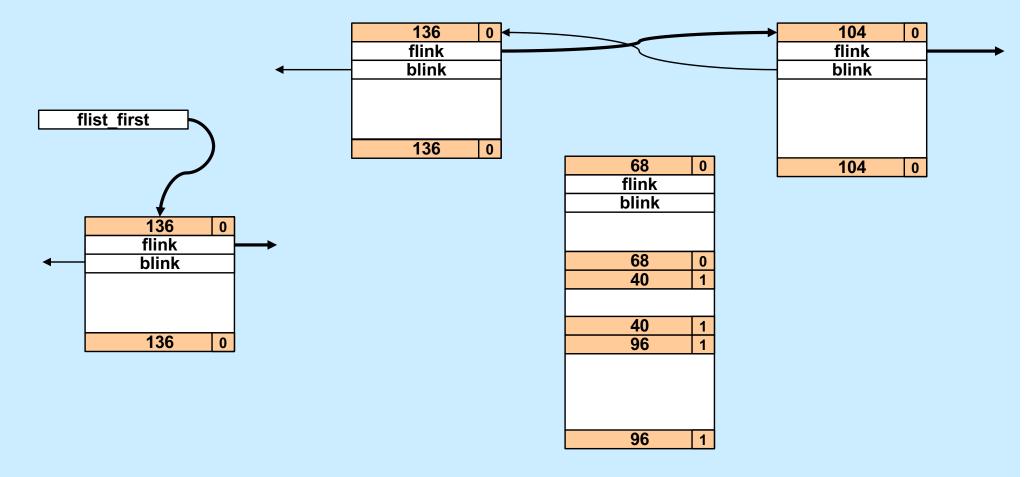


- We are freeing a block
  - is the previous block free?
  - is the next block free?
  - are both free?

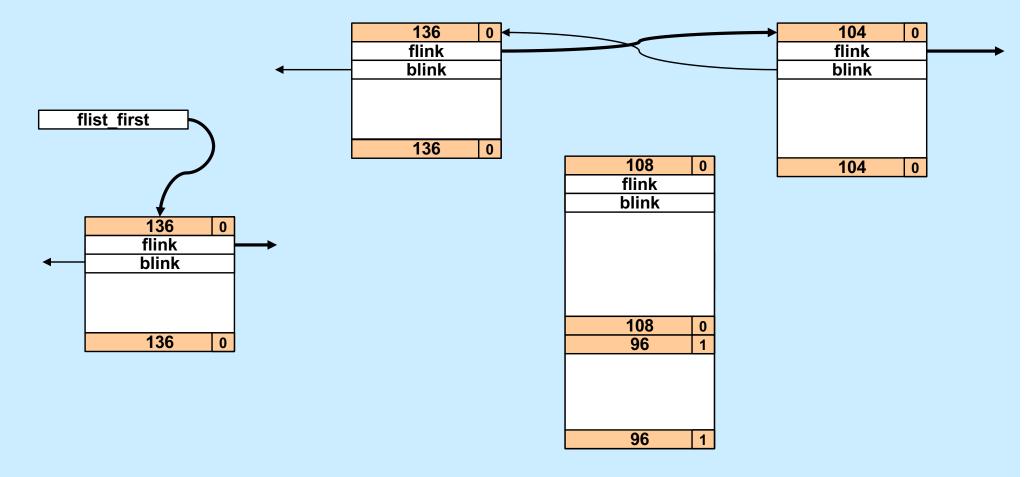
### **Coalescing: Previous Free (1)**



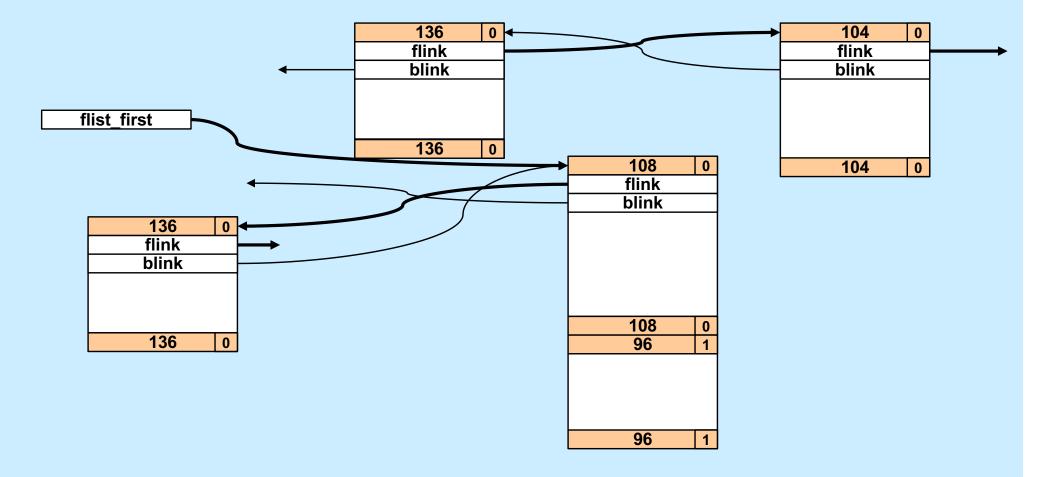
# **Coalescing: Previous Free (2)**



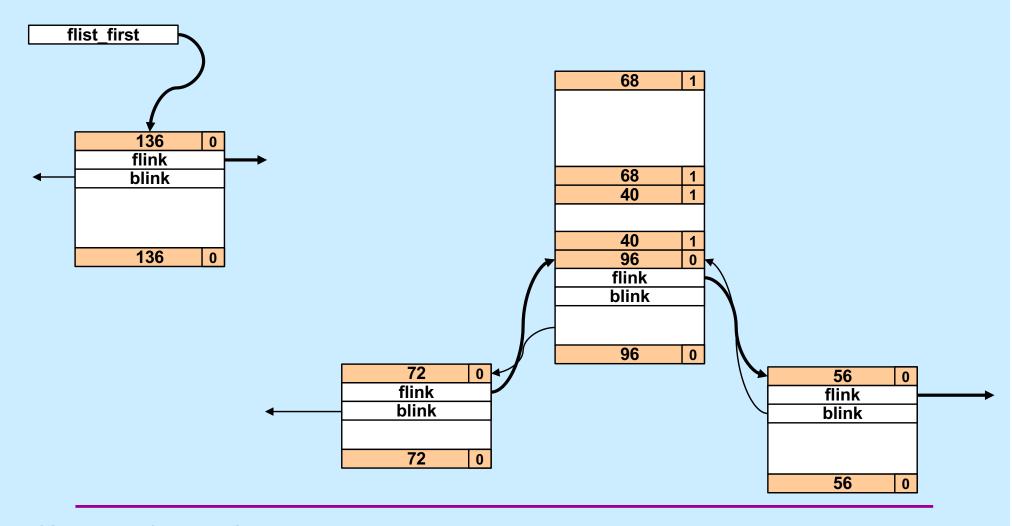
# **Coalescing: Previous Free (3)**



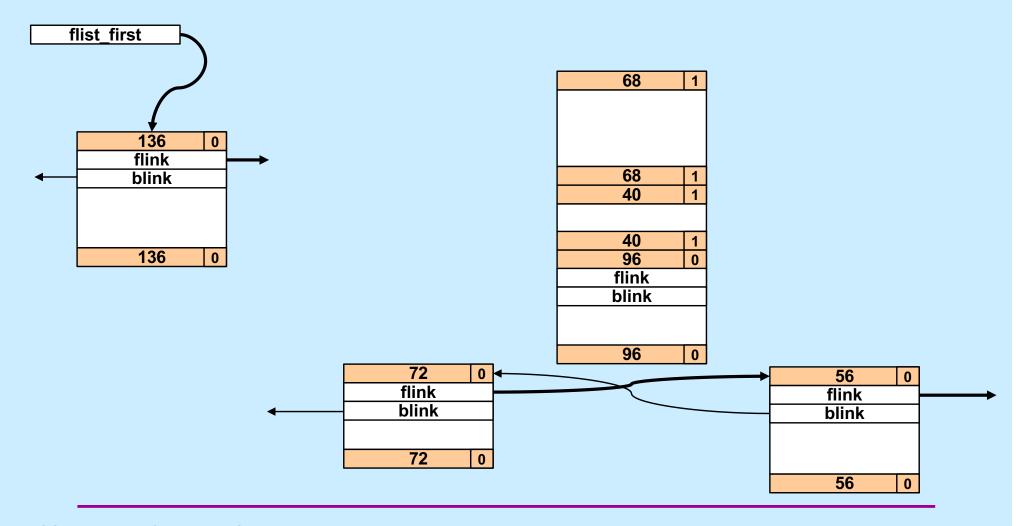
## **Coalescing: Previous Free (4)**



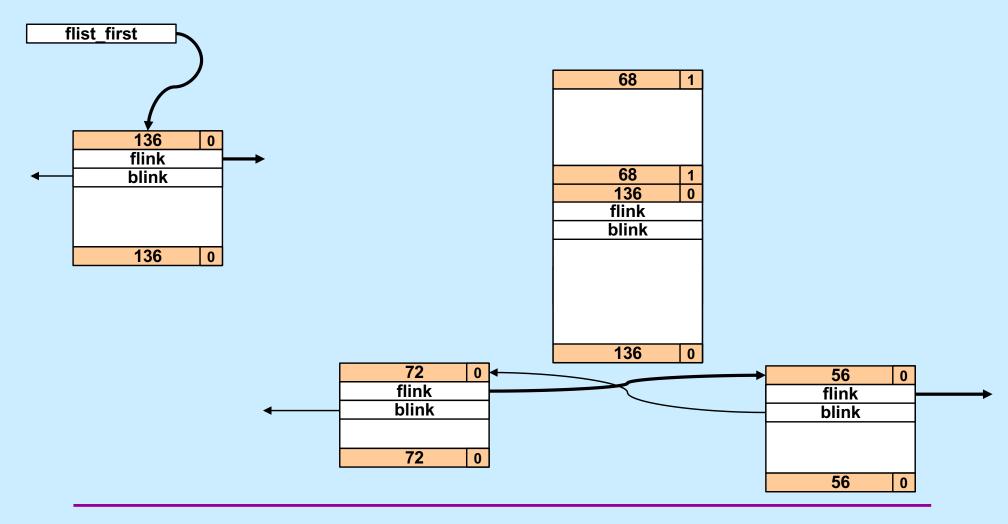
## **Coalescing: Next Free (1)**



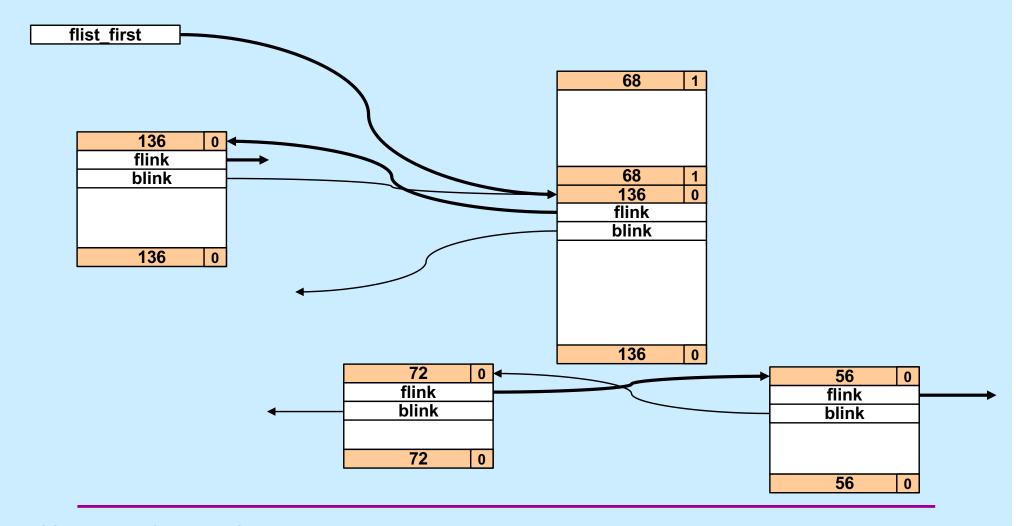
# **Coalescing: Next Free (2)**



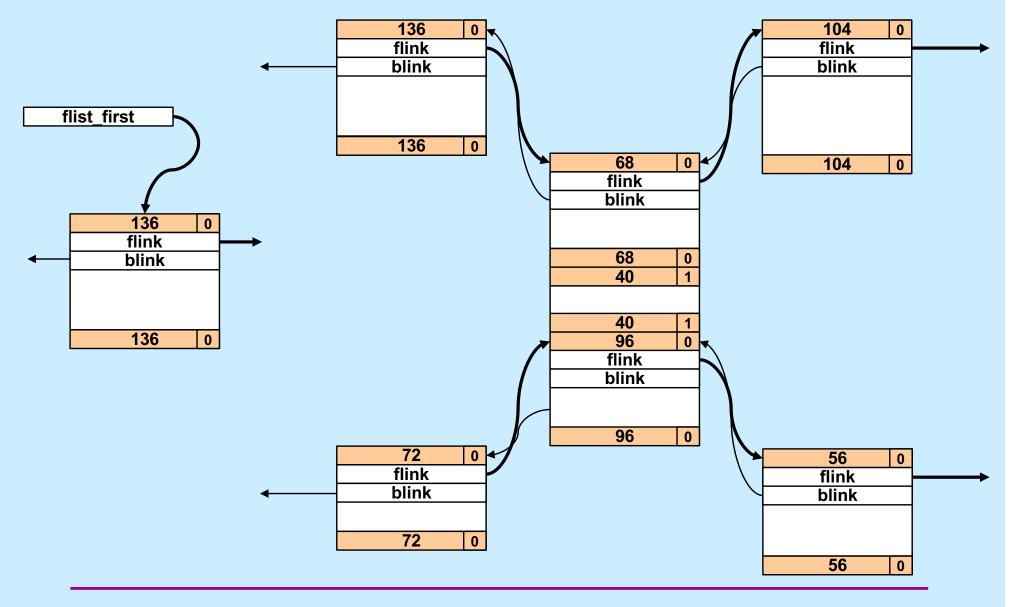
## **Coalescing: Next Free (3)**



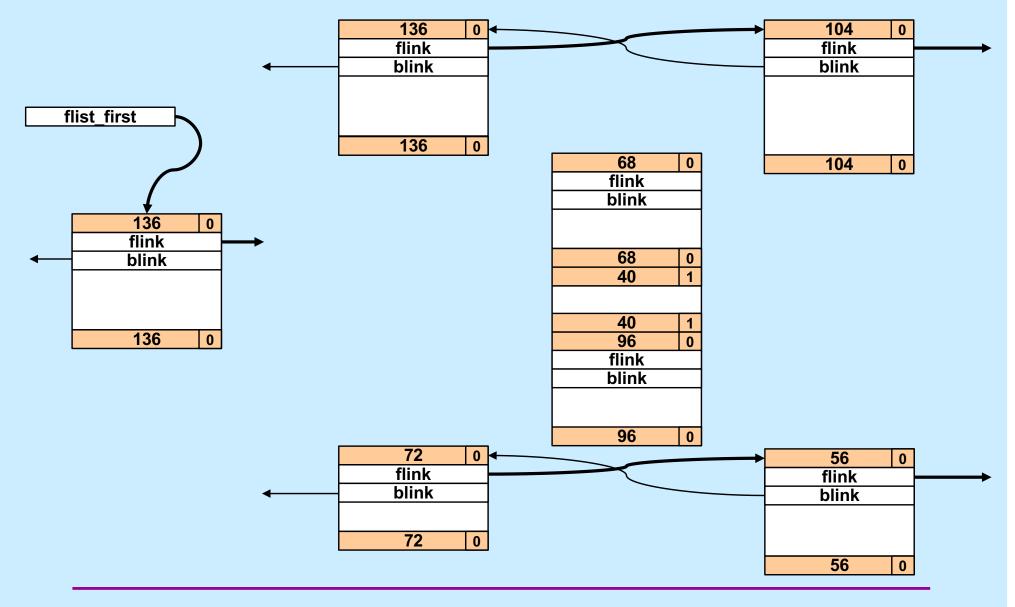
# **Coalescing: Next Free (4)**



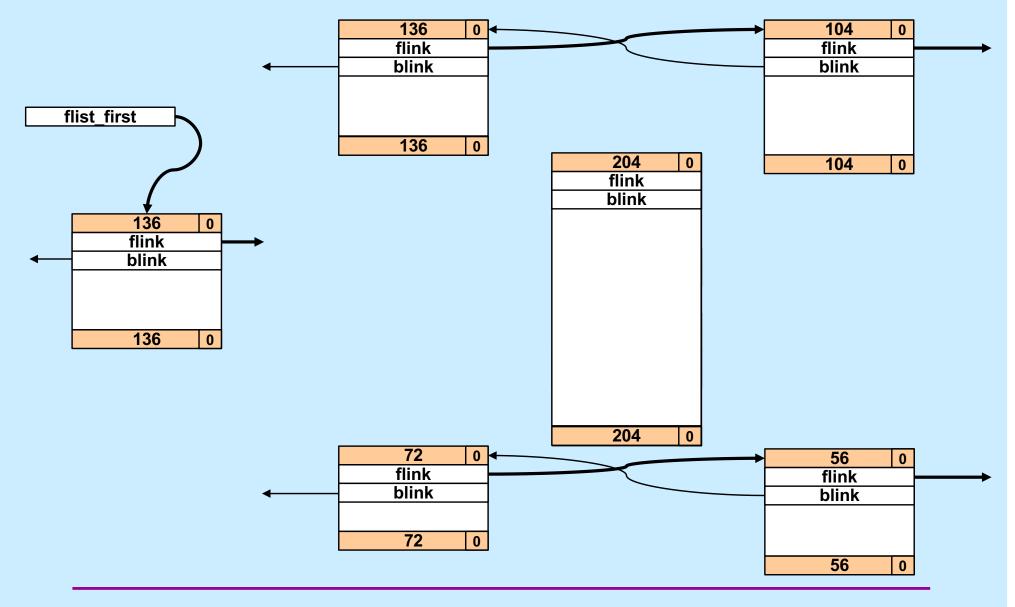
# **Coalescing: Both Free (1)**



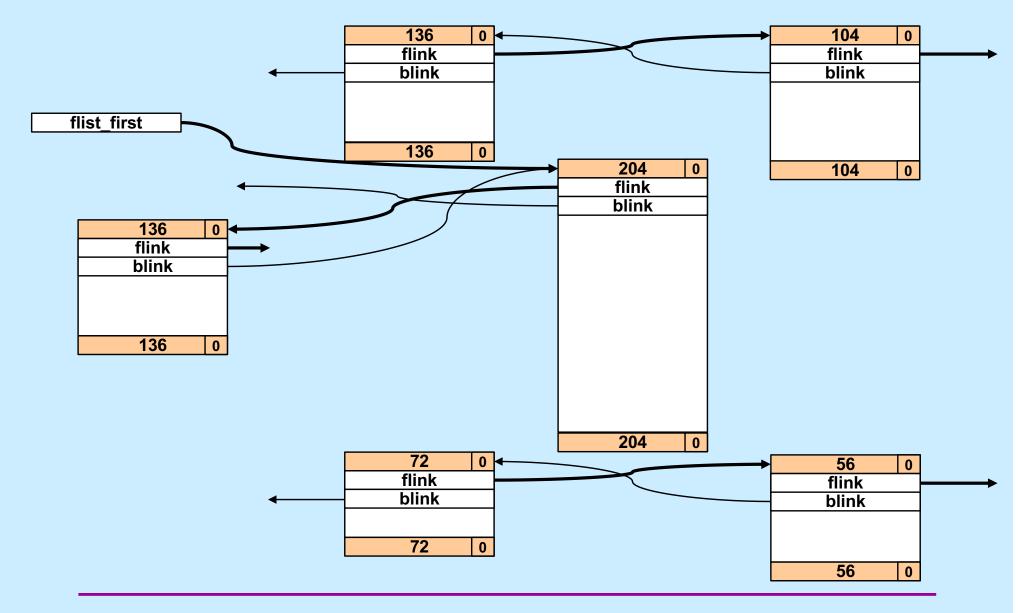
# Coalescing: Both Free (2)



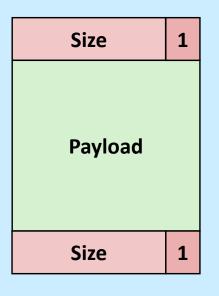
# Coalescing: Both Free (3)

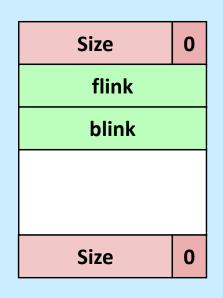


# **Coalescing: Both Free (4)**



#### C vs. Storage Allocation





```
typedef struct block {
  long size;
  long payload[size/8 - 2];
  long end_size;
} block_t;
```

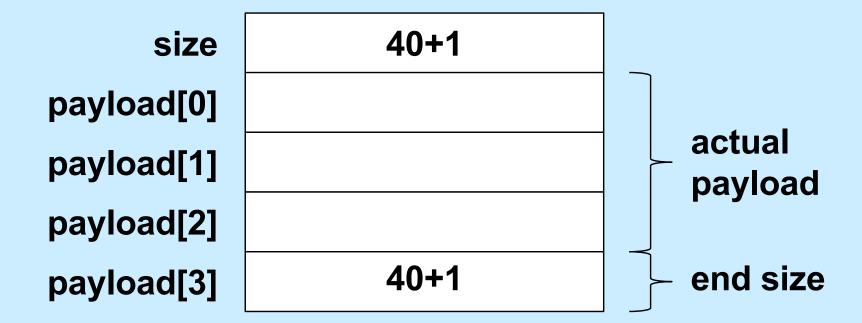
```
typedef struct free_block {
  long size;
  struct free_block *flink;
  struct free_block *blink;
  long filler[size/8 - 4];
  long end_size;
} free_block_t;
```

## **Overcoming C**

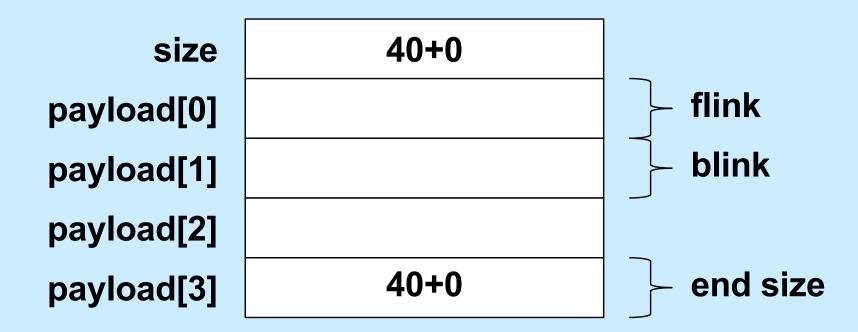
- Think objects
  - a block is an object
    - » opaque to the outside world
  - define accessor functions to get and set its contents

```
typedef struct block {
    size_t size;
    size_t payload[0];
} block_t;
```

#### **Allocated Block**



#### Free Block



In general, end size is at payload[size/8 – 2]

### **Overloading Size**

Size

a

```
size_t block_allocated(block_t *b) {
  return b->size & 1;
}

size_t block_size(block_t *b) {
  return b->size & -2;
}
```

#### **End Size**

```
Size a

payload[0]

payload[1]

...

payload[Size/8 - 3]

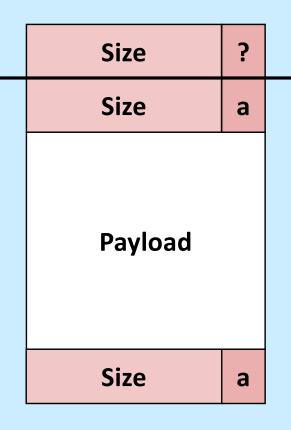
payload[Size/8 - 2] end size
```

```
size_t *block_end_tag(block_t *b) {
  return &b->payload[b->size/8 - 2];
}
```

### **Setting the Size**

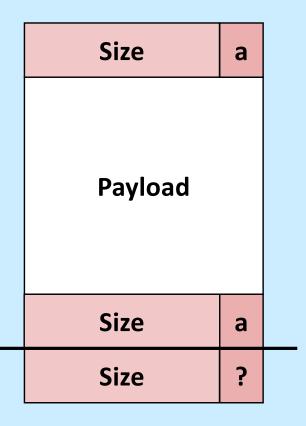
```
void block set size(block t *b, size t size) {
  assert(!(size & 7)); // multiple of 8
  size |= block allocated(b); // preserve alloc bit
 b->size = size;
  *block end tag(b) = size;
void block set allocated(block_t *b, size_t a) {
  assert((a == 0) | | (a == 1));
  if (a) {
   b->size = 1;
    *block end tag(b) |=1;
  } else {
   b->size \&= -2;
    *block end tag(b) \&= -2;
```

## Is Previous Adjacent Block Free?



```
size_t block_prev_allocated(
    block_t *b) {
    return b->payload[-2] & 1;
}
```

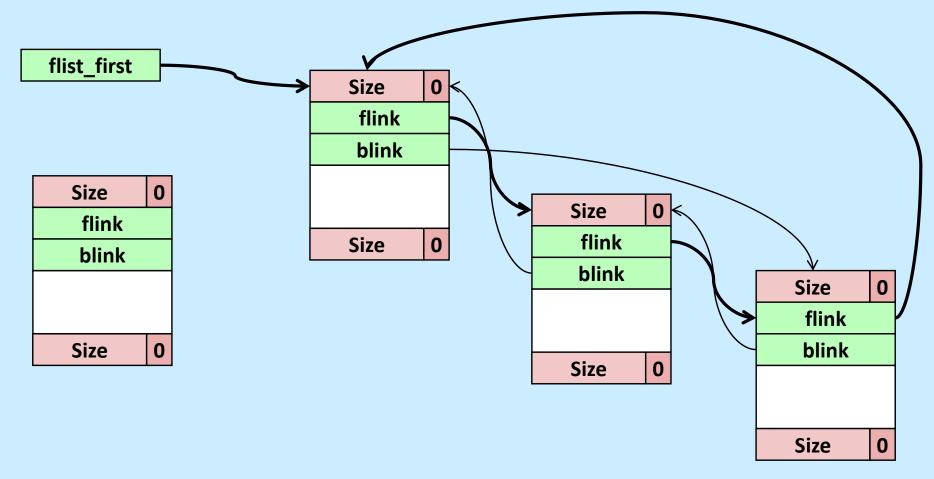
## Is Next Adjacent Block Free?



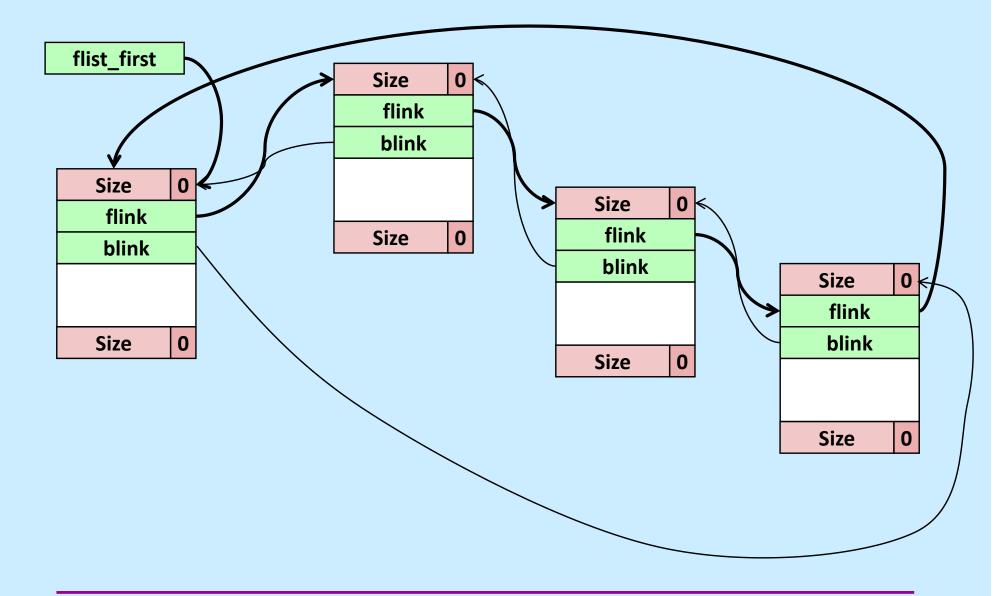
```
block_t *block_next(
    block_t *b) {
    return (block_t *)
        ((char *)b + block_size(b));
}

size_t block_next_allocated(
    block_t *b) {
    return block_allocated(
        block_next(b));
}
```

# Adding a Block to the Free List (1)



# Adding a Block to the Free List (2)



## **Accessing the Object**

```
block t *block flink(block t *b) {
  return (block t *)b->payload[0];
void block set flink(block t *b, block t *next) {
  b->payload[0] = (size t) next;
block t *block blink(block t *b) {
  return (block t *)b->payload[1];
void block set blink(block t *b, block t *next) {
  b->payload[1] = (size t) next;
```

#### **Insertion Code**

```
void insert free block(block t *fb) {
  assert(!block allocated(fb));
  if (flist first != NULL) {
    block t *last =
      block blink(flist first);
    block set flink(fb, flist first);
    block set blink(fb, last);
    block set flink(last, fb);
    block set blink(flist first, fb);
  } else {
    block set flink(fb, fb);
    block set blink(fb, fb);
  flist first = fb;
```

#### **Performance**

- Won't all the calls to the accessor functions slow things down a lot?
  - yes not just a lot, but tons
- Why not use macros (#define) instead?
  - the textbook does this
  - it makes the code impossible to debug
    - » gdb shows only the name of the macro, not its body
- What to do????

#### **Inline Functions**

```
static inline size_t block_size(
    block_t *b) {
    return b->size & -2;
}
```

- when debugging (–O0), the code is implemented as a normal function
  - » easy to debug with gdb
- when optimized (–O1, –O2), calls to the function are replaced with the body of the function
  - » no function-call overhead

# **Prolog and Epilog**

