

CS 33

Multithreaded Programming II

Start/Stop



- **Start/Stop interface**

```
void wait_for_start(state_t *s);
```

```
void start(state_t *s);
```

```
void stop(state_t *s);
```

Start/Stop



- **Start/Stop interface**

```
void wait_for_start(state_t *s) {  
    if (s->state == stopped)  
        sleep();  
}  
  
void start(state_t *s) {  
    state = started;  
    wakeup_all();  
}  
  
void stop(state_t *s) {  
    state = stopped;  
}
```

Start/Stop

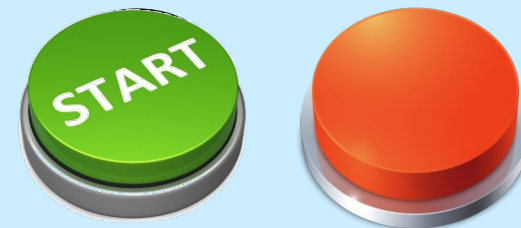


- **Start/Stop interface**

```
void wait_for_start(state_t *s) {
    pthread_mutex_lock(&s->mutex);
    if (s->state == stopped) {
        pthread_mutex_unlock(&s->mutex);
        sleep();
    } else pthread_mutex_unlock(&s->mutex);
}

void start(state_t *s) {
    pthread_mutex_lock(&s->mutex);
    state = started;
    wakeup_all();
    pthread_mutex_unlock(&s->mutex);
}
```

Start/Stop

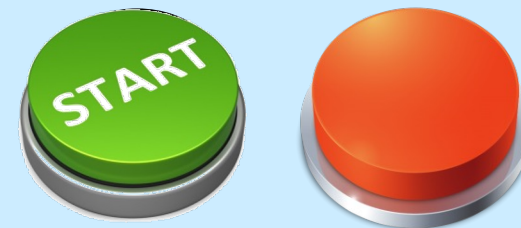


- **Start/Stop interface**

```
void wait_for_start(state_t *s) {
    pthread_mutex_lock(&s->mutex);
    if (s->state == stopped) {
        sleep();
    }
    pthread_mutex_unlock(&s->mutex);
}

void start(state_t *s) {
    pthread_mutex_lock(&s->mutex);
    state = started;
    wakeup_all();
    pthread_mutex_unlock(&s->mutex);
}
```

Start/Stop



- **Start/Stop interface**

```
void wait_for_start(state_t *s) {  
    pthread_mutex_lock(&s->mutex);  
    while (s->state == stopped)  
        pthread_cond_wait(&s->queue, &s->mutex);  
    pthread_mutex_unlock(&s->mutex);  
}  
  
void start(state_t *s) {  
    pthread_mutex_lock(&s->mutex);  
    s->state = started;  
    pthread_cond_broadcast(&s->queue);  
    pthread_mutex_unlock(&s->mutex);  
}
```

Condition Variables

```
when (guard) [  
    statement 1;  
    ...  
    statement n;  
]
```

```
// code modifying the guard:  
...
```

```
pthread_mutex_lock(&mutex);  
while (!guard)  
    pthread_cond_wait(  
        &cond_var, &mutex);  
statement 1;  
...  
statement n;  
pthread_mutex_unlock(&mutex);
```

```
pthread_mutex_lock(&mutex);  
// code modifying the guard:  
...  
pthread_cond_broadcast(  
    &cond_var);  
pthread_mutex_unlock(&mutex);
```

Set Up

```
int pthread_cond_init(pthread_cond_t *cvp,  
    pthread_condattr_t *attrp)
```

```
int pthread_cond_destroy(pthread_cond_t *cvp)
```

```
int pthread_condattr_init(pthread_condattr_t *attrp)
```

```
int pthread_condattr_destroy(pthread_condattr_t *attrp)
```


PC with Condition Variables (1)

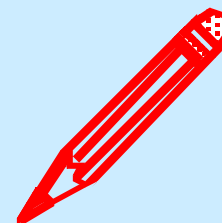
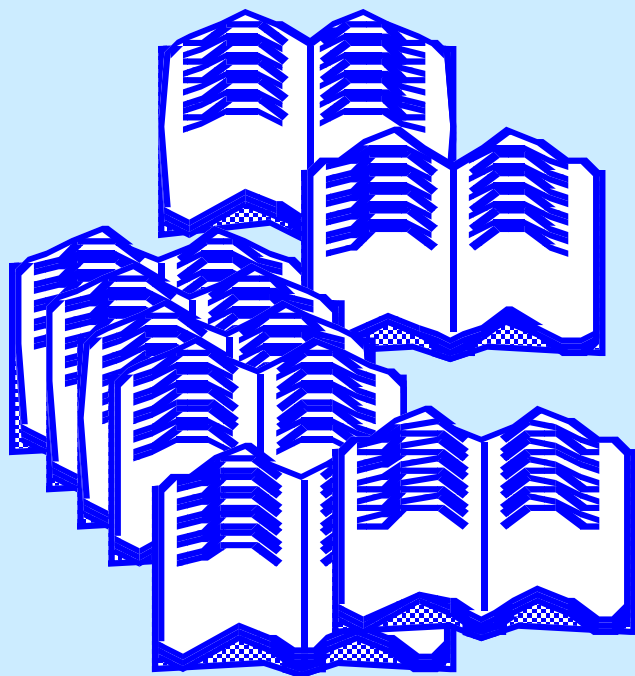
```
typedef struct buffer {  
    pthread_mutex_t m;  
    pthread_cond_t more_space;  
    pthread_cond_t more_items;  
    int next_in;  
    int next_out;  
    int empty;  
    char buf[BSIZE];  
} buffer_t;
```

PC with Condition Variables (2)

```
void produce(buffer_t *b,
             char item) {
    pthread_mutex_lock(&b->m);
    while (!(b->empty > 0))
        pthread_cond_wait(
            &b->more_space, &b->m);
    b->buf[b->nextin] = item;
    if (++(b->nextin) == BSIZE)
        b->nextin = 0;
    b->empty--;
    pthread_cond_signal(
        &b->more_items);
    pthread_mutex_unlock(&b->m);
}
```

```
char consume(buffer_t *b) {
    char item;
    pthread_mutex_lock(&b->m);
    while (!(b->empty < BSIZE))
        pthread_cond_wait(
            &b->more_items, &b->m);
    item = b->buf[b->nextout];
    if (++(b->nextout) == BSIZE)
        b->nextout = 0;
    b->empty++;
    pthread_cond_signal(
        &b->more_space);
    pthread_mutex_unlock(&b->m);
    return item;
}
```

Readers-Writers Problem



Pseudocode

```
reader( ) {  
    when (writers == 0) [  
        readers++;  
    ]  
  
    /* read */  
  
    [readers--;]  
}
```

```
writer( ) {  
    when ((writers == 0) &&  
        (readers == 0)) [  
        writers++;  
    ]  
  
    /* write */  
  
    [writers--;]  
}
```

Pseudocode with Assertions

```
reader( ) {  
    when (writers == 0) [  
        readers++;  
    ]  
  
    assert((writers == 0) &&  
        (readers > 0));  
    /* read */  
  
    [readers--;]  
}
```

```
writer( ) {  
    when ((writers == 0) &&  
        (readers == 0)) [  
        writers++;  
    ]  
  
    assert((readers == 0) &&  
        (writers == 1));  
    /* write */  
  
    [writers--;]  
}
```

Solution with POSIX Threads

```
reader( ) {
    pthread_mutex_lock(&m);
    while (!(writers == 0))
        pthread_cond_wait(
            &readersQ, &m);
    readers++;
    pthread_mutex_unlock(&m);
    /* read */
    pthread_mutex_lock(&m);
    if (--readers == 0)
        pthread_cond_signal(
            &writersQ);
    pthread_mutex_unlock(&m);
}
```

```
writer( ) {
    pthread_mutex_lock(&m);
    while (!(readers == 0) &&
        (writers == 0))
        pthread_cond_wait(
            &writersQ, &m);
    writers++;
    pthread_mutex_unlock(&m);
    /* write */
    pthread_mutex_lock(&m);
    writers--;
    pthread_cond_signal(
        &writersQ);
    pthread_cond_broadcast(
        &readersQ);
    pthread_mutex_unlock(&m);
}
```

Quiz 1

If a thread calls *writer*, will it eventually return from *writer* (assuming well behaved threads)?

- a) yes, always
- b) it will usually return, but it's possible that it will not return
- c) it might return, but it's highly likely that it will never return
- d) no, never

New Pseudocode

```
reader( ) {  
    when (writers == 0) [  
        readers++;  
    ]  
  
    /* read */  
  
    [readers--;]  
}
```

```
writer( ) {  
    [writers++;]  
    when ((readers == 0) &&  
        (active_writers == 0)) [  
        active_writers++;  
    ]  
  
    /* write */  
  
    [writers--;  
    active_writers--;]  
}
```


Improved Reader

```
reader( ) {  
    pthread_mutex_lock(&m);  
  
    while (!(writers == 0)) {  
        pthread_cond_wait(  
            &readersQ, &m);  
    }  
    readers++;  
  
    pthread_mutex_unlock(&m);  
  
    /* read */
```

```
pthread_mutex_lock(&m);  
  
    if (--readers == 0)  
        pthread_cond_signal(  
            &writersQ);  
  
    pthread_mutex_unlock(&m);  
}
```

Improved Writer

```
writer( ) {
    pthread_mutex_lock(&m);

    writers++;
    while (!(readers == 0) &&
           (active_writers == 0)) {
        pthread_cond_wait(
            &writersQ, &m);
    }
    active_writers++;

    pthread_mutex_unlock(&m);

    /* write */
```

```
pthread_mutex_lock(&m);

writers--;
    active_writers--;
if (writers)
    pthread_cond_signal(
        &writersQ);
else
    pthread_cond_broadcast(
        &readersQ);

pthread_mutex_unlock(&m);
}
```

Quiz 2

If a thread calls *reader*, will it eventually return from *reader* (assuming well behaved threads)?

- a) yes, always
- b) it will usually return, but it's possible that it will not return
- c) it might return, but it's highly likely that it will never return
- d) no, never

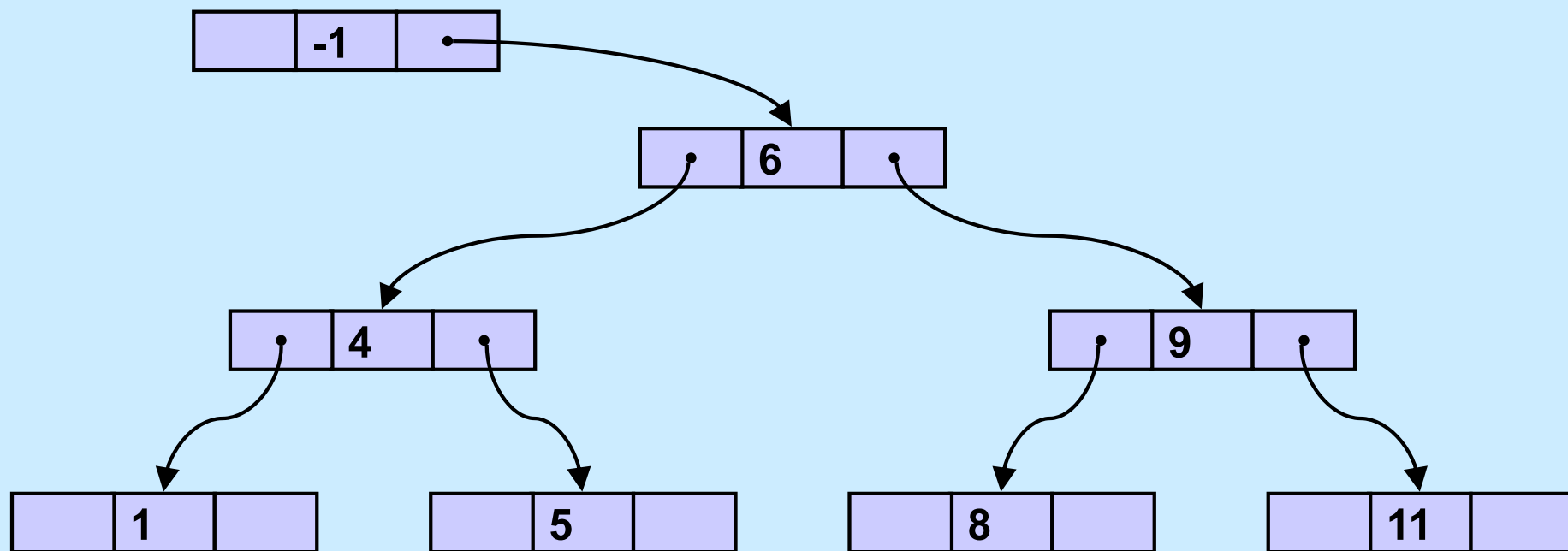
New, From POSIX!

```
int pthread_rwlock_init(pthread_rwlock_t *lock,  
    pthread_rwlockattr_t *att);  
int pthread_rwlock_destroy(pthread_rwlock_t *lock);  
int pthread_rwlock_rdlock(pthread_rwlock_t *lock);  
int pthread_rwlock_wrlock(pthread_rwlock_t *lock);  
int pthread_rwlock_tryrdlock(pthread_rwlock_t *lock);  
int pthread_rwlock_trywrlock(pthread_rwlock_t *lock);  
int pthread_timedrwlock_rdlock(pthread_rwlock_t *lock,  
    struct timespec *ts);  
int pthread_timedrwlock_wrlock(pthread_rwlock_t *lock,  
    struct timespec *ts);  
int pthread_rwlock_unlock(pthread_rwlock_t *lock);
```

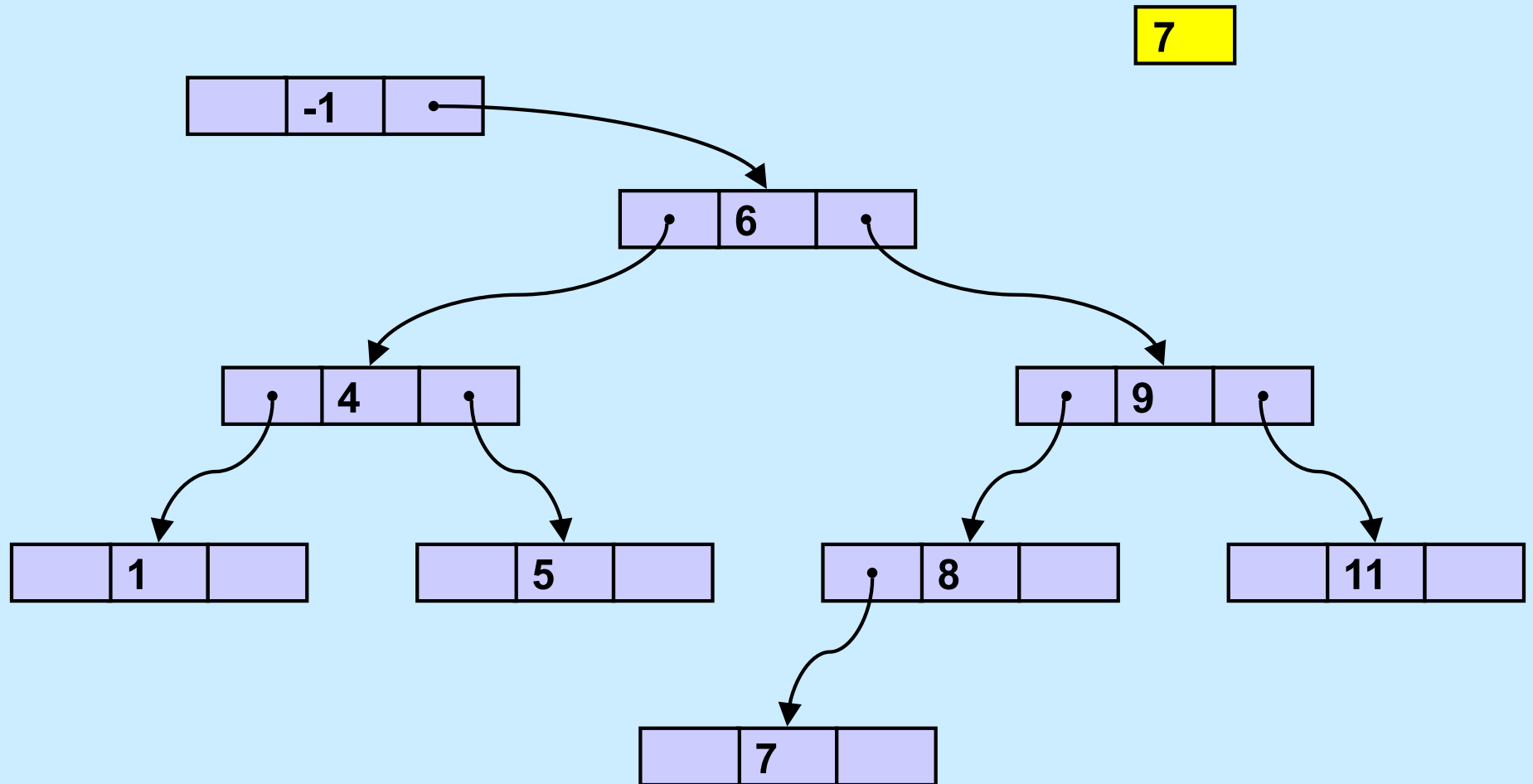
Quiz 3

- **Missing in the *rwlock* API is a function to “upgrade” a readers lock into a writers lock. It’s not included because**
 - a) it’s rarely needed, so there’s no point to including it**
 - b) the same effect could be achieved by unlocking the readers lock, then taking a writers lock**
 - c) using such a function would likely result in deadlock**

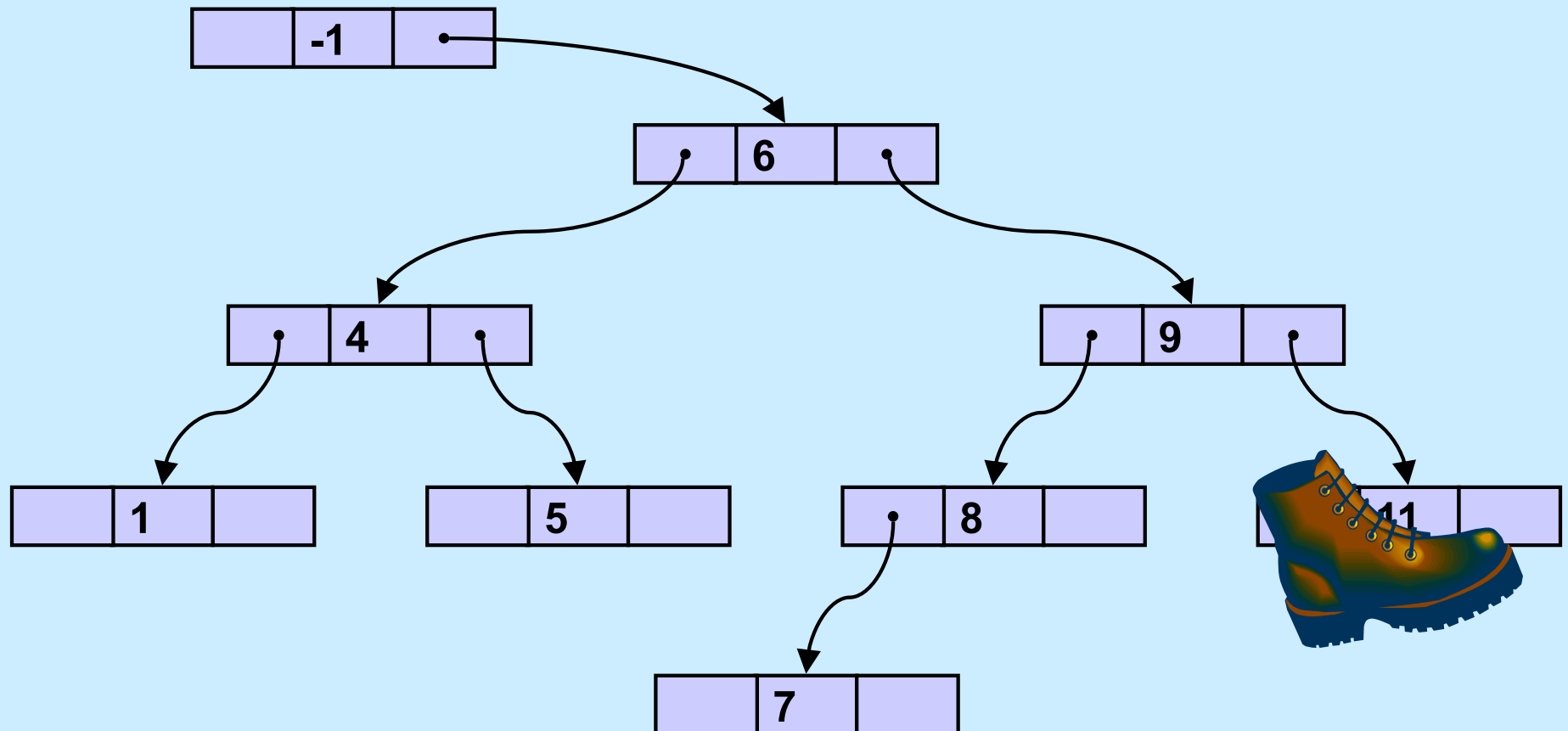
Binary Search Tree



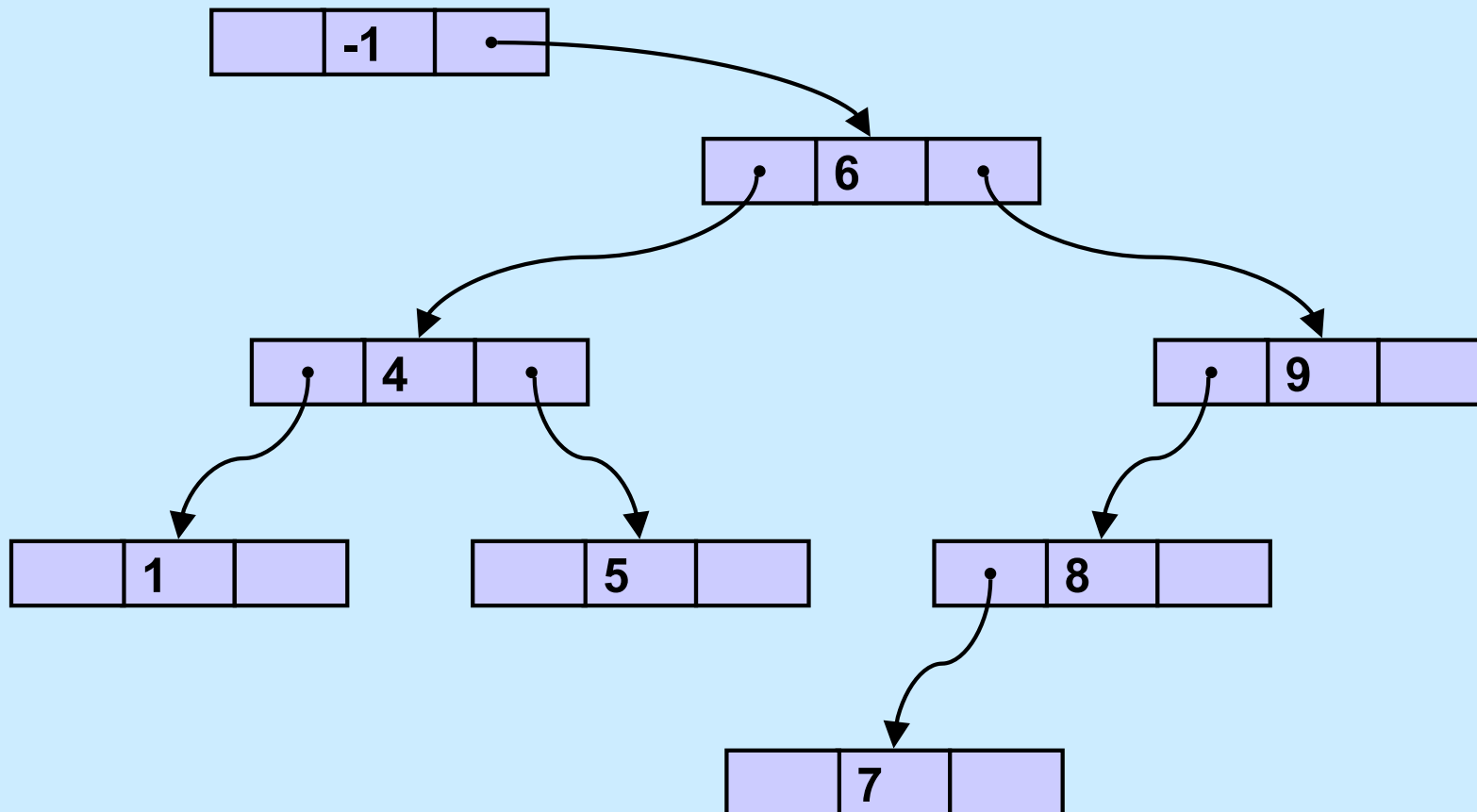
Binary Search Tree: Insertion



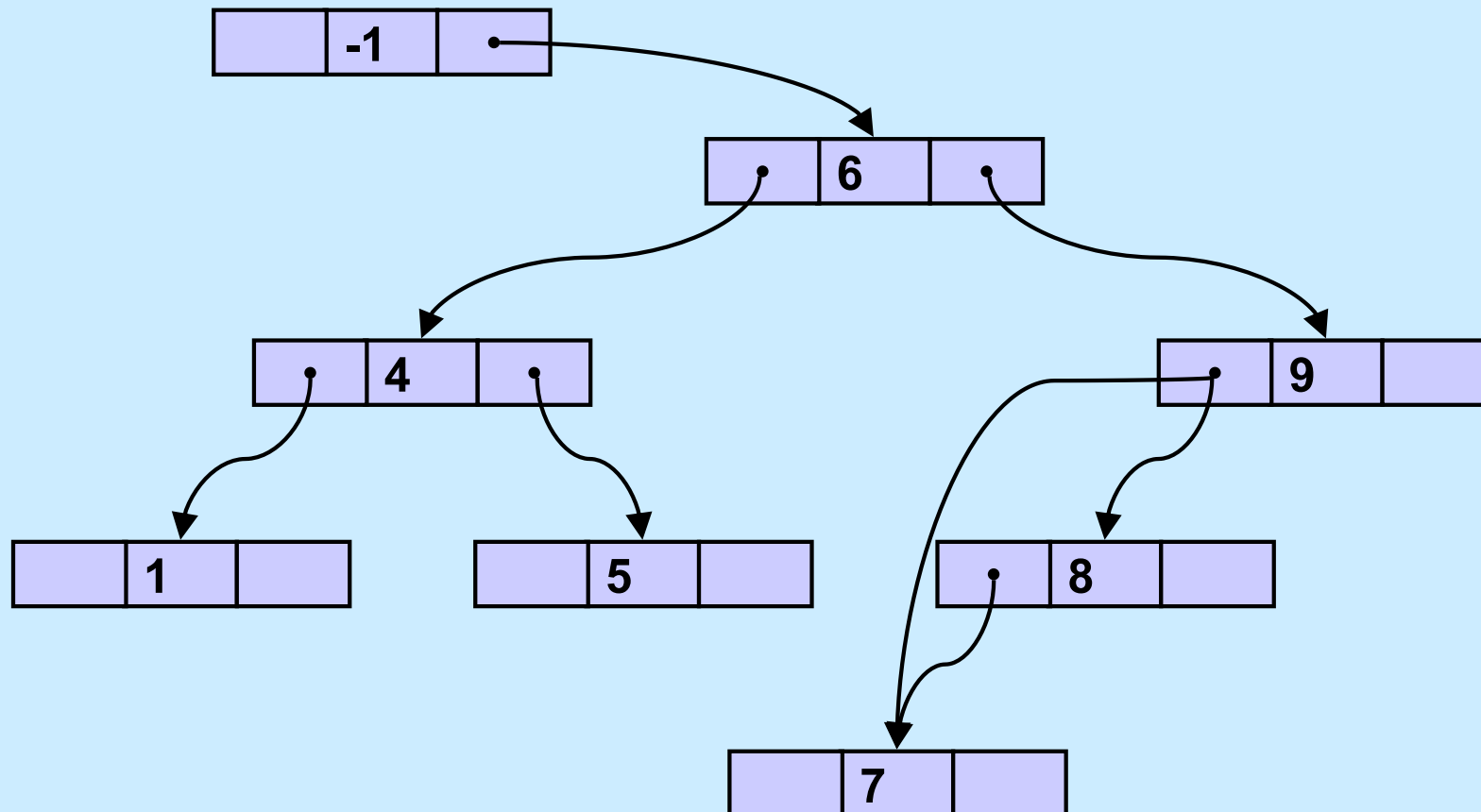
Binary Search Tree: Deletion of Leaf



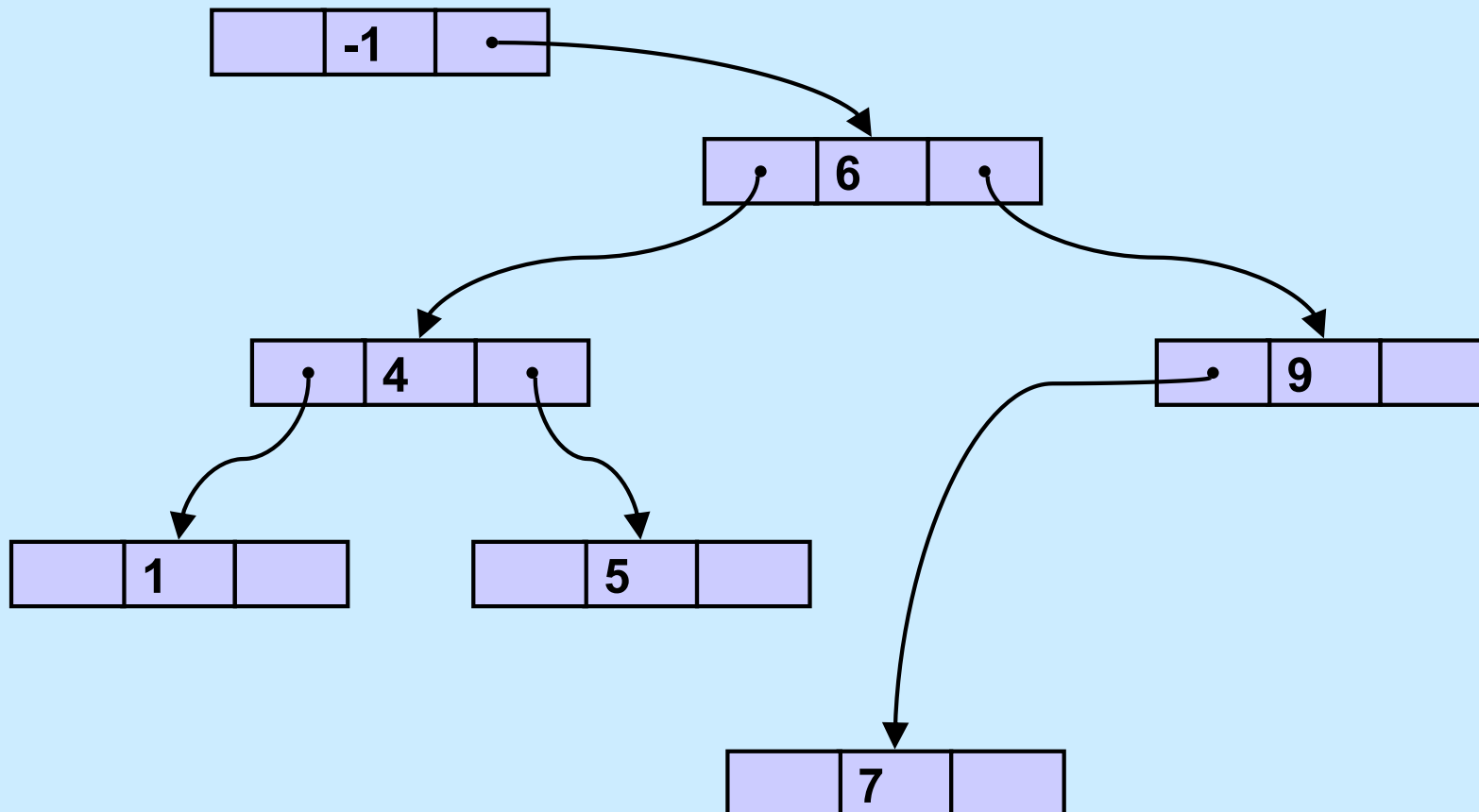
Binary Search Tree: Deletion of Leaf



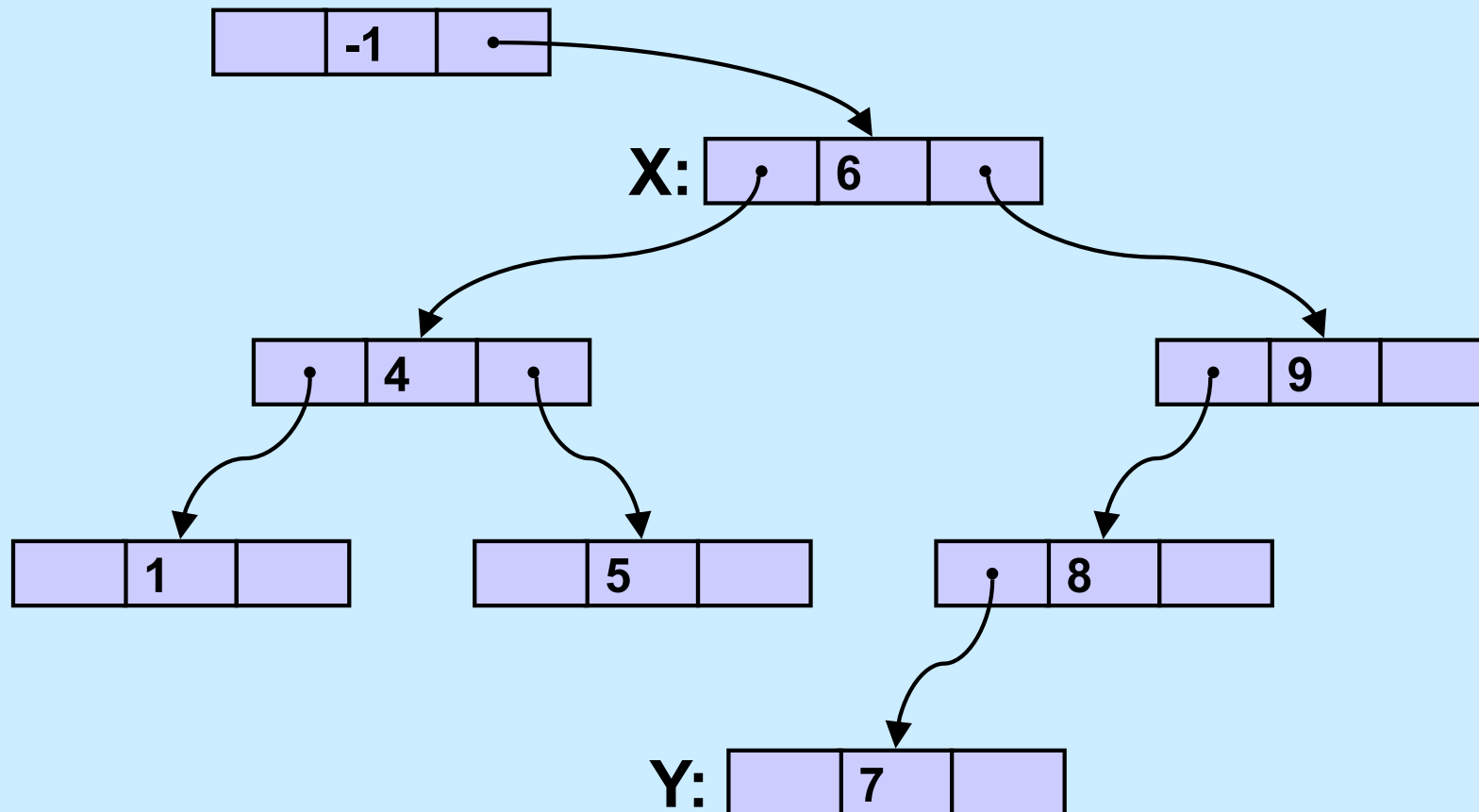
Binary Search Tree: Deletion of Node with One Child



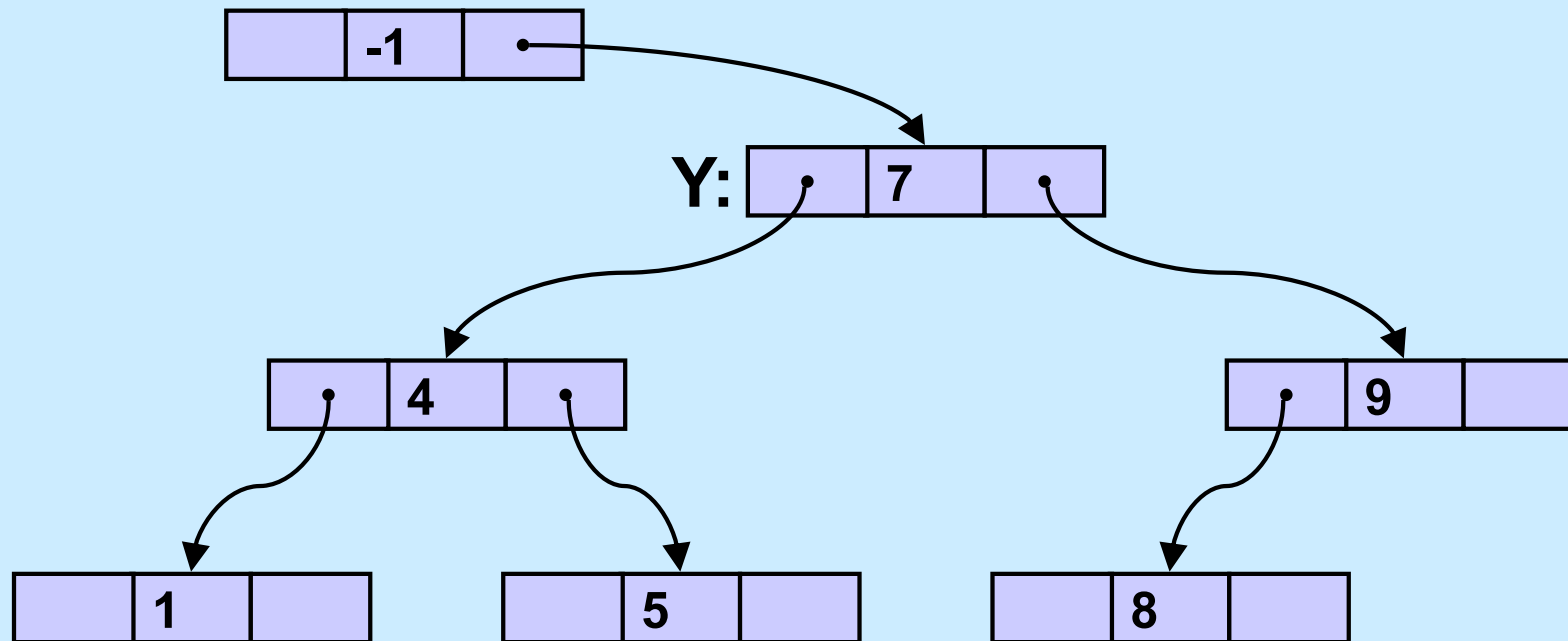
Binary Search Tree: Deletion of Node with One Child



Binary Search Tree: Deletion of Node with Two Children



Binary Search Tree: Deletion of Node with Two Children



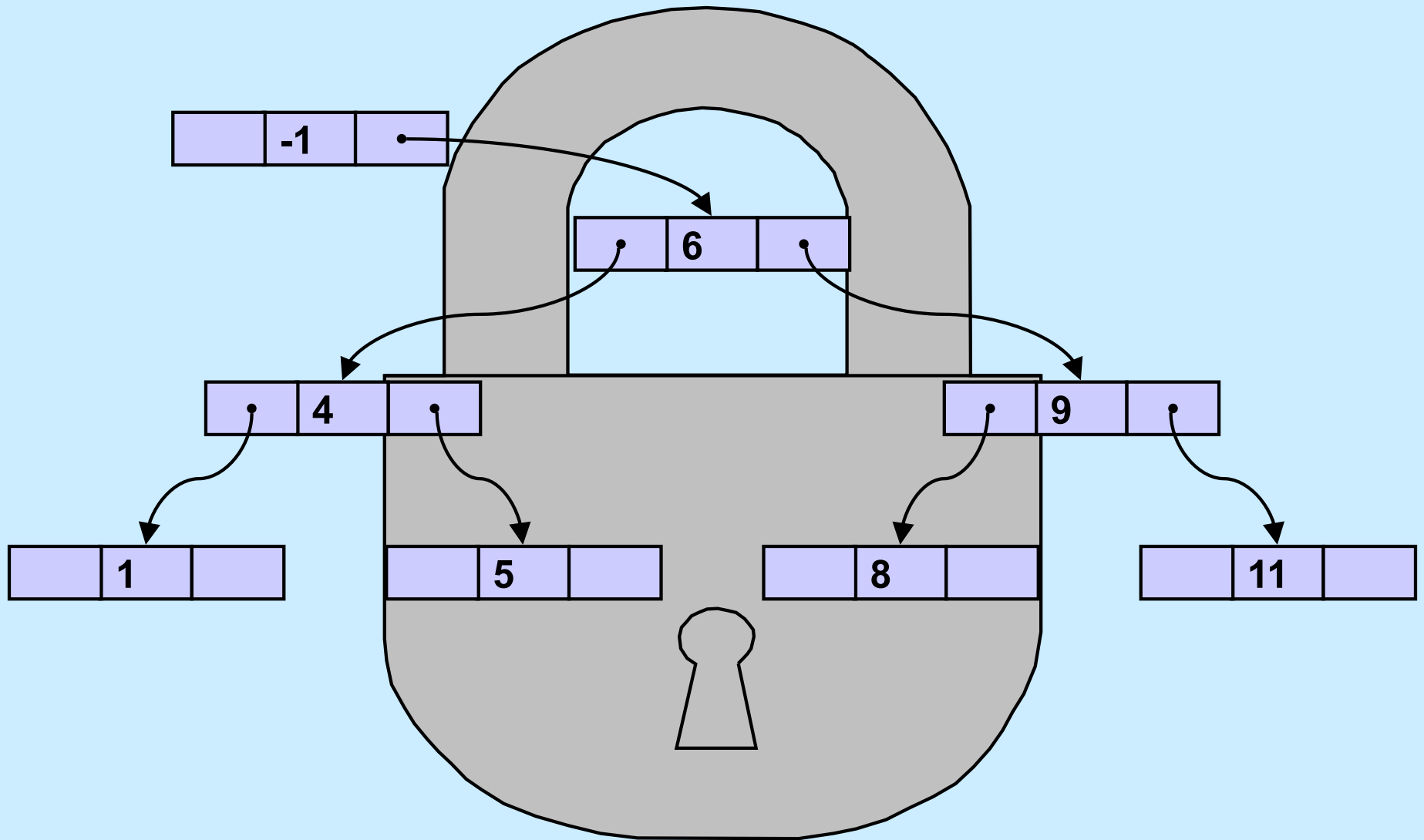
C Code: Search

```
Node *search(int key,
             Node *parent, Node **parentp) {
    Node *next;
    Node *result;
    if (key < parent->key) {
        if ((next = parent->lchild)
            == 0) {
            result = 0;
        } else {
            if (key == next->key) {
                result = next;
            } else {
                result = search(key,
                               next, parentpp);
            }
            return result;
        }
    }
    } else {
        if ((next = parent->rchild)
            == 0) {
            result = 0;
        } else {
            if (key == next->key) {
                result = next;
            } else {
                result = search(key,
                               next, parentpp);
            }
            return result;
        }
    }
    if (parentpp != 0)
        *parentpp = parent;
    return result;
}
```

C Code: Add

```
int add(int key) {
    Node *parent, *target, *newnode;
    if ((target = search(key, &head, &parent)) != 0) {
        return 0;
    }
    newnode = malloc(sizeof(Node));
    newnode->key = key;
    newnode->lchild = newnode->rchild = 0;
    if (name < parent->name)
        parent->lchild = newnode;
    else
        parent->rchild = newnode;
    return 1;
}
```

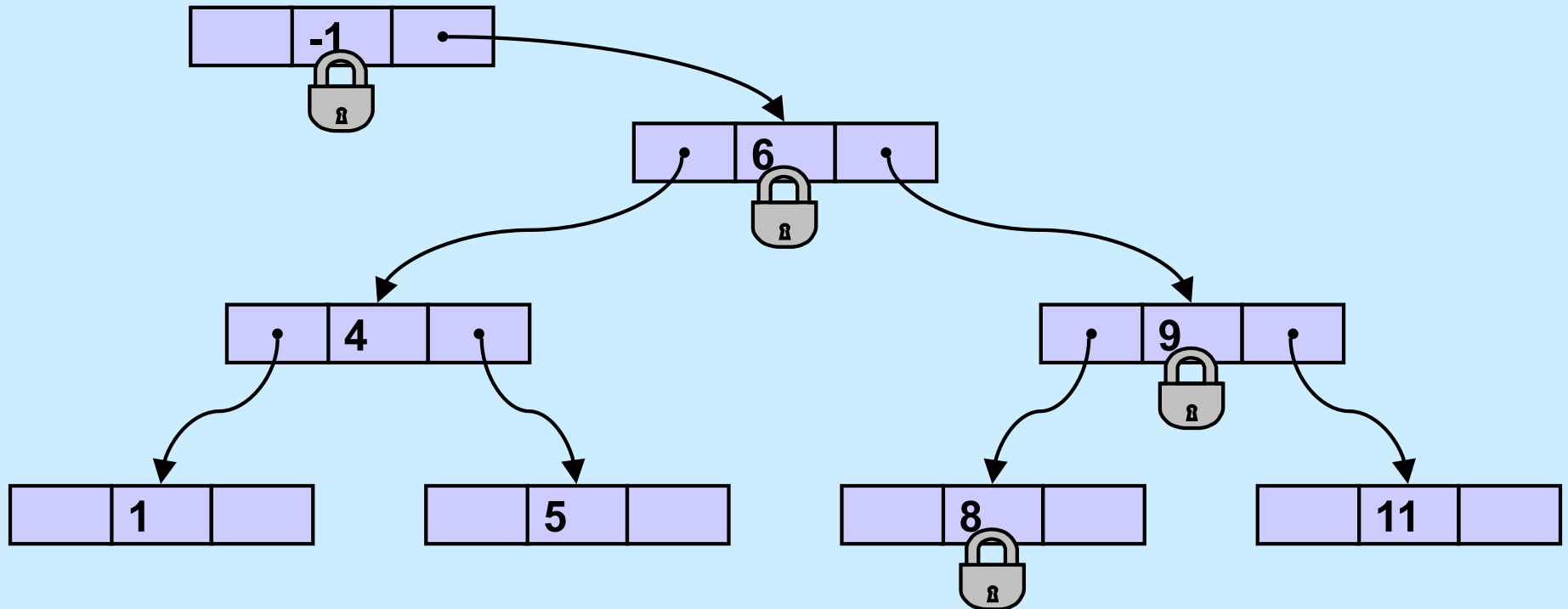
Binary Search Tree with Coarse-Grained Synchronization



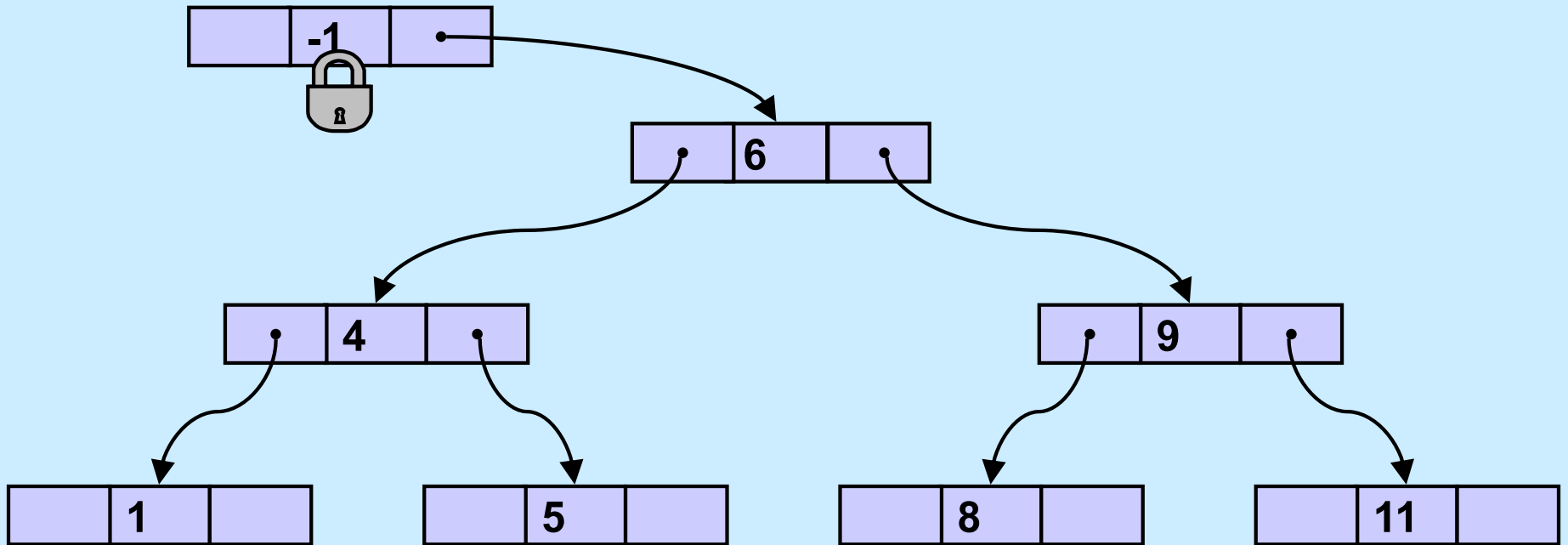
C Code: Add with Coarse-Grained Synchronization

```
int add(int key) {
    Node *parent, *target, *newnode;
    pthread_rwlock_wrlock(&tree_lock);
    if ((target = search(key, &head, &parent)) != 0) {
        pthread_rwlock_unlock(&tree_lock);
        return 0;
    }
    newnode = malloc(sizeof(Node));
    newnode->key = key;
    newnode->lchild = newnode->rchild = 0;
    if (name < parent->name)
        parent->lchild = newnode;
    else
        parent->rchild = newnode;
    pthread_rwlock_unlock(&tree_lock);
    return 1;
}
```

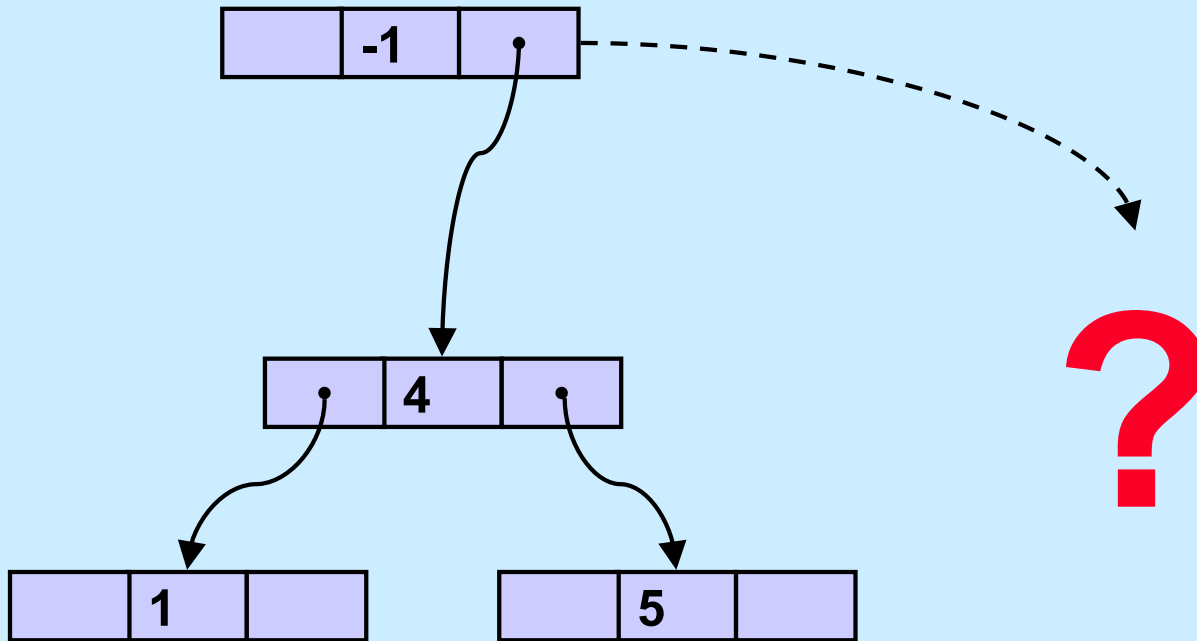
Binary Search Tree with Fine-Grained Synchronization I



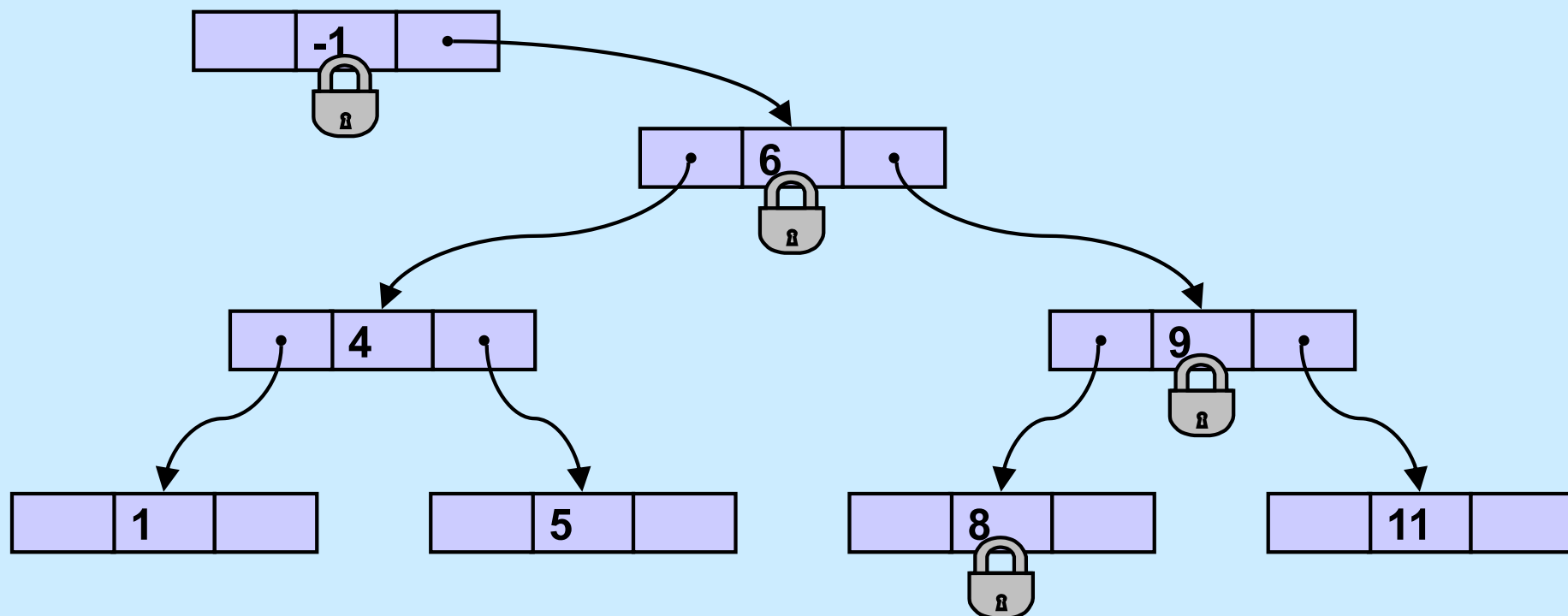
Binary Search Tree with Fine-Grained Synchronization II



Binary Search Tree with Fine-Grained Synchronization III



Doing It Right ...



C Code: Fine-Grained Search I

```
enum locktype {l_read, l_write};

#define lock(lt, lk) ((lt) == l_read)?
    pthread_rwlock_rdlock(lk):
    pthread_rwlock_wrlock(lk)

Node *search(int key,
             Node *parent, Node **parentp,
             enum locktype lt) {
    // parent is locked on entry
    Node *next;
    Node *result;
    if (key < parent->key) {
        if ((next = parent->lchild)
            == 0) {
            result = 0;
        } else {
            lock(lt, &next->lock);
            if (key == next->key) {
                result = next;
            } else {
                pthread_rwlock_unlock(
                    &parent->lock);
                result = search(key,
                               next, parentp, lt);
            }
            return result;
        }
    }
}
```

C Code: Fine-Grained Search II

```
} else {
    if ((next = parent->rchild)
        == 0) {
        result = 0;
    } else {
        lock(lt, &next->lock);
        if (key == next->key) {
            result = next;
        } else {
            pthread_rwlock_unlock(
                &parent->lock);
            result = search(key,
                next, parentpp, lt);
            return result;
        }
    }
}
if (parentpp != 0) {
    // parent remains locked
    *parentpp = parent;
} else
    pthread_rwlock_unlock(
        &parent->lock);
return result;
}
```

Quiz 4

The search function takes read locks if the purpose of the search is for a query, but takes write locks if the purpose is for an add or a delete. Would it make sense for it always to take read locks until it reaches the target of the search, then take a write lock just for that target?

- a) Yes, since doing so allows more concurrency**
- b) No, it would work, but there would be no increase in concurrency**
- c) No, it would not work**

C Code: Add with Fine-Grained Synchronization I

```
int add(int key) {  
    Node *parent, *target, *newnode;  
    pthread_rwlock_wrlock(&head->lock);  
    if ((target = search(key, &head, &parent,  
        l_write)) != 0) {  
        pthread_rwlock_unlock(&target->lock);  
        pthread_rwlock_unlock(&parent->lock);  
        return 0;  
    }  
}
```

C Code: Add with Fine-Grained Synchronization II

```
newnode = malloc(sizeof(Node));
newnode->key = key;
newnode->lchild = newnode->rchild = 0;
pthread_rwlock_init(&newnode->lock, 0);
if (name < parent->name)
    parent->lchild = newnode;
else
    parent->rchild = newnode;
pthread_rwlock_unlock(&parent->lock);
return 1;
}
```

Quiz 5

The add function calls malloc. Could we use the malloc that you'll finish by Wednesday for this, or do we need a different one that's safe for use in multithreaded programs?

- a) Since the calling thread has a write lock on the parent of the new node, it's safe to call the standard malloc**
- b) Even if the calling thread didn't have a write lock on the parent, it would be safe to call the the standard malloc**
- c) We will need a new malloc, one that's safe for use in multithreaded programs**